OSSIM Mapping ARchive OMAR™ Users Guide

Version 1.8.16 June 05 2013

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1.0 (U) Points of Contact

(U) OMAR is developed by RadiantBlue Technologies, Inc. and is supported by a team that is reachable by email or phone.

(U) For those accessing the OMAR to view NTM imagery/FMV on JWICS or SIPR, you have 24x7 access to the Technology Stewards at 571-721-7287.

(U) For those accessing other instantiations of OMAR, or for general inquiries, please contact the following:

Name	Role	Email Address
Dennis O'Connor	Help Desk 321-473-4316	doconnor@radiantBlue.com

2.0 (U) Overview

(U) Welcome to OMAR (**O**SSIM **M**apping **AR**chive), a service that allows the user to search, locate and view airborne and satellite imagery as well as full motion video (FMV).

(U) OMAR allows users access to full resolution imagery pixels even on lowbandwidth networks through the use of Web Mapping Service (WMS). Rather than providing the entire picture at once, OMAR returns only the information requested by the user at any given time (i.e. enough pixels to fill the screen, e.g. 100 KB per screen vs. 400 MB for a file). Imagery is processed in real-time through OMAR's OSSIM library and users can sharpen and adjust the contrast of images as necessary, letting the web server do the work, freeing up valuable Desktop CPU resources.

(U) OMAR is based on the Open Source Software Image Map (OSSIM), an Open Source Geospatial Foundation (OSGeo - <u>http://www.osgeo.org/ossim</u>) project. OSSIM is a high performance engine for remote sensing, image processing, geographical information systems and photogrammetry. OMAR integrates other open source software products such as Apache Tomcat, Open Layers, MapServer, GRAILS, GEOServer, PostGIS and Postgres, among others.

2.1 (U) Feedback

(U) Users may leave feedback in the *Report* section of the *Home* page or may email the OMAR group directly (see <u>Points of Contact</u>).

All Feedback is greatly encouraged and deeply appreciated!!

(U) Typographical Conventions

(U) Typographical conventions found in this User Guide.

Convention	Description
Bold Text	Indicates a user action, such as selecting a link or an action button
Italics	Identifies a specific section, window or function within the current view

3.0 (U) Getting Started

Note: go to 16.0 to view how to do a quick start query.

(U) OMAR can be accessed via a WMS layer interface or a GEOINT tool capable of employing KML network links (i.e. Google Earth, ArcGIS, etc). There are no hardware requirements to use OMAR however we recommend Mozilla Firefox 3.0 or higher and Internet Explorer 7.0 or higher; additionally, flash is required for video playback. Regardless of which method is used, all users must first self-register an account in OMAR.

(U) To create an account:

Unclassified		
OMAR Ossim Map	M ping ARchive	
	About OMAR	
	Please Login	
	Login ID	
	Password	
	Remember me	
	Login	
	Click here to register Forgot Password	

(U) Navigate to http://omar in a web browser.¹

Figure 1. Login Screen

(U) At the OMAR login page, select **Click here to register** to create your OMAR account.

(U) In the *User Registration* window, complete all required information, including a valid email address. The email address should be consistent with the level of the system where you are accessing OMAR (e.g., a SIPR address is you are accessing OMAR on the SIPR network).

(U)When an account is created, OMAR will send a verification email to the email address provided.

¹ The actual URL will vary depending on the specific OMAR application being accessed.

A Home	
Create a new account:	
Username	
Full Name	
Organization	
Phone Number	
E-Mail	
E-mail (again)	
Password	
Password (again)	
💼 Create your account	

Figure 2: OMAR User Registration Screen

(U) After logging in, the *Home* page appears (Figure 3). This page provides the primary top level choices for OMAR operation:

- Search Section 3
- Paragraph 3.6; Section 4 Browse • Section 7
- KML Network Links •
- GeoRSS Links •
- Enter individual preferences **User Preferences** •
- Report •
- Logout

Enter user feedback Stop the OMAR application

Unclassified

		Uncla	ssified	
				Logout
Search:				
	Imagery <u>Video</u>			
Browse:				
	Imagery <u>Video</u>			
KML Network	Links:			
\bigcirc	10 Most Recent Images for View 10 Most Recent Videos for View 30 Most Recent Days Imagery Coverage 30 Most Recent Days Video Coverage			
GeoRSS Links				
	By Country Code			
User Preferen	ces:			
	Edit Profile Change Password			
Report:				
1	<u>User Feedback</u> <u>View Feedback</u>			
Logout				
•				
		Unclas	ssified	

Figure 3: OMAR Home Page

(U) An admin user has two additional sections available in the *Home* page (Figure 4). These sections provide the following functionality:

- User Management administration of users
- Edit Tables

direct access to database table content

User Managem	User Management:				
	<u>User</u> <u>Roles</u> <u>Permissions</u>				
Edit Tables:					
	Scripts ChipFormat Report Repository WmsLayers WmsLog GetTileLog RasterDataSet RasterEntry RasterEntryFile RasterEntrySearchTag RasterFile VideoDataSet VideoDataSetSearchTag VideoFile				

Figure 4: OMAR Home Page, Admin Functions

4.0 (U) Federated Searching Imagery

(U) There are different ways that a user can do a federated search using OMAR.

(U) Federated search came about to meet the need of searching multiple content sources with one query. This allows a user to search multiple databases at once in real time, arrange the results from the various databases into a useful form and then present the results to the user.

4.1 (U) Geographic Criteria

(U) OMAR provides four options to search geographically by specifying either bounding box, point radius, date/time, query or map.

(U) Note: Input the geographical coordinates in the following formats by selecting the appropriate *Display Unit* drop-down menu at the top of the page:

- Decimal Degrees (DD),
- Degrees, Minutes, Seconds (DMS),
- Military Grid Reference System (MGRS)

4.2 (U) B Search for images on bound Box

(U) This option is used to search imagery based on a bounding box of a specified size.

- *Lower Left* southwestern coordinate of bounding box
- Upper Right northeastern coordinate of bounding box
- *Clear Bound Box* action button to clear the contents of the bound box

OMAR™ EXPORT SEARCH
Jnits DD 💠
Search For: 💿 Raster 🔵 Video
✓ Use Spatial
 Use Bound Box
Bound Box Search:
Lower-Left Lat/Lon:
-159.2578125,-236.6015625
Upper-Right Lat/Lon:
159.2578125,236.6015625
OUse Point Radius
Point Radius Search:
Center Lat/Lon:
0,0
Radius in Meters:
0

4.3(U) Search for images on Point Radius

(U) This option is used to search imagery based on a circle with a specified center and radius.

- *Map Center* enter coordinates to specify the center of the search
- *Radius in Meters* radius to specify the extent of the search
- Set Map Center action button to center the map based on the coordinates specified

Jnits DD +			
Search For: 💿 Raster 🔵 Video			
🗹 Use Spatial			
OUse Bound Box			
Bound Box Search:			
Lower-Left Lat/Lon:			
-125.7718125,-170.9005625			
Upper-Right Lat/Lon:			
192.7438125,302.3025625			
• Use Point Radius			
Point Radius Search:			
Center Lat/Lon:			
33.486,65.701			
Radius in Meters:			
1			

(U) Search for images on Time

4.3.1 (U) Date/Time Criteria

(U) This option is used to search imagery within a specific timeframe.

- *Start Date/Time* oldest date/time for which OMAR will search for imagery
- Stop Date/Time most recent date/time for which OMAR will search for imagery



4.4 (U) Search Using Query

	Query	Мар	ngaiost
Named Queries 🗧 🗧			
And + +0	\$		
Reset Apply and Validate Show	/		

(U) Below lists all of the different Medata Records that can be query on. They can be use one at a time or stringed together for a better more accurate query.

4.4.1 (U) Metadata Criteria

Raw CQL Record ID BE IID2 Class Name Country File Type Filename IID Mission NIIRS Sensor

Target ID Image Representation Azimuth Angle **Grazing Angle** Acquisition Date Access Date Ingest Date Receive Date Ground Geom " Entry Id Width Height Number of Bands Number of Res Levels GSD Units GSD X GSD Y Bit Depth Data Type Index ID Product Id ICAT Security Classification Security Code Isource Organization Description Wac Code Sun Elevation Sun Azimuth **Cloud Cover** Exclude Policy

Min Lat / Lon Max Lat / Lon Center Lat / Lon

4.5 (U) Searching Using the Map

(U) After selecting **Imagery** from the *Search* section of the *Home* page, the *Imagery Search* page is displayed. The bright colored polygons (aka footprints) on the globe

represent areas that have been imaged and are in the OMAR database. The footprint colors are keyed based on the legend in the right panel.

(U) When no search criterion is entered, as in this case, all OMAR imagery that is contained within the bounding box on the screen is returned in date/time order starting with the most recent image.

(U) Note: Panning around the map or zooming to a different location after setting the map center, will cause the *Map Center* input box to update with the new center.



Unclassified



5.0 (U) Export

5.1 (U) Keyhole Markup Language (KML Query)

OMAR™	EXPORT SEAR	сн
18.28092		46875
Jpper-Right	KML Query	
58.00748	KML Query Float Bbox	0625
💽 Use Po	KML	
Point Radiu	GeoJSON	
Center Lat/	GML2	
38.14420	csv	375
Radius in M	Timelapse	
1	GeoCell Project Package	

(U) Keyhole Markup Language (KML) is an <u>XML</u> notation for expressing geographic annotation and visualization within <u>Internet</u>-based, two-dimensional maps and three-dimensional <u>Earth</u> browsers. KML was developed for use with <u>Google Earth</u>, which was originally named Keyhole Earth Viewer. It was created by <u>Keyhole</u>, <u>Inc</u>, which was acquired by <u>Google</u> in 2004. KML became an international standard of the <u>Open Geospatial Consortium</u> in 2008.^{[1][2]} Google Earth was the first program able to view and graphically edit KML files. Other projects such as <u>Marble</u> have also started to develop KML support.[[]

(U) When an AOI is selected from the map, that query will be open and displayed in Google Earth.

5.2 (U) Keyhole Markup Language (KML Query Float Bbox)

(U) Is the same KML query but has a JavaScript library for displaying windowed content over top of web pages

(U) When an AOI is selected from the map that query will be open and displayed in Google Earth

5.3 (U) GeoJSON

(U) GeoJSON allows geographic data to be stored in a human-readable way that is generally more compact than <u>XML</u>.

(U) When an AOI is selected from the map that query will be open and display XML.

5.4 (U) GML - Geography Markup Language

(U) The **Geography Markup Language** (**GML**) is the <u>XML</u> grammar defined by the <u>Open Geospatial Consortium</u> (OGC) to express geographical features. GML serves as a modeling language for geographic systems as well as an open interchange format for geographic transactions on the Internet. Note that the concept of feature in GML is a very general one and includes not only conventional "vector" or discrete objects, but also coverage's and sensor data. The ability to integrate all forms of geographic information is key to the utility of GML.

(U) When GML is selected it can be open in a browser like Firefox and will display an XML text.

5.5 (U) Comma-separated values (CSV)

(U) A **comma-separated values** (**CSV**) file stores <u>tabular</u> data (numbers and text) in plain-text form. <u>Plain text</u> means that the file is a sequence of <u>characters</u>, with no data that has to be interpreted instead, as binary numbers. A CSV file consists of any number of <u>records</u>, separated by line breaks of some kind; each record consists of <u>fields</u>, separated by some other character or string, most commonly a literal comma or <u>tab</u>.

(U) CSV can be open in a number of different applications.

5.6 (U) Timelapse

(U) Timelapse is used not from the map as the others exports but is used from a completed query display



(U) A user will select images that cover the same AOI, and then the user will select Timelapse to play the images. You can see that images 481 and 479 are selected



(U) After Timelapse is selected then the Timelapse displayed and you are able to see the play button at the bottom of the display. There is a zoom button at the top left of the display that a user can zoom in or out of the display.

5.7 (U) GeoCell Project Package

(U) A user will select images to be downloaded to the client platform for use in the GeoCell exploitation tool. GeoCell is a stand-alone executable program that can be used for a number of advanced exploitation operations (e.g. registration, change detection, etc.).

(U) After "GeoCell Project Package" is selected, a message will appear that states that export has been initiated. The user must remain on the search page while a zip archive containing all image support files is created. When archiving is complete, a standard download window appears and the user can either press *Save File* or *Cancel*. After the zip file is downloaded, the user can unzip the archive or move it to a different location.

(U) After the file has been unzipped there will be a .geom, .ovr, .his and image file (and other support files for selected image types) for each image that was selected. The <u>GeoCell User Manual</u> may be consulted for information regarding GeoCell operations.

6.0 (U) Navigation Bar

(U) The *Navigation Bar* found at the top of the *Search* page provides a variety of functions that allows the user to navigate through the world map. Hover over any of the ten buttons in the *Navigation Bar* to view their function.



Click and drag to pan map Click and drag to zoom into an area Click to zoom in Click to zoom out Click to zoom to full resolution Click to zoom to the max extent

Unclassified



🚟 Measure polygon area

7.0 (U) Map Measurement Tool

(U) The *Map Measurement Tool* is use in conjunction with the *path length* and *polygon area* tools on the Navigation bar to measure distance or area.

7.1 (U) Measuring Path Length

- (U) Select the desired unit from the *Map Measurement Tool* drop-down menu.
- (U) Select the *path length* tool from the Navigation bar.
- (U) Move the cursor onto the map and click a point for the path start.
- (U) Move the cursor to the desired end point and double click to complete the path.
- (U) Note the distance in the area under the unit's drop-down menu.

7.2 (U) Measuring Polygon Area

- (U) Select the desired unit from the Map Measurement Tool drop-down menu
- (U) Select the *polygon area* **b** tool from the Navigation bar.
- (U) Move the cursor onto the map and click a point to start the polygon.
- (U) Move the cursor to the next location on the map and click to establish the next vertex of the polygon. Note: A polygon requires a minimum of 3 vertices.
- (U) Close the polygon by double-clicking on the start point.
- (U) Note the area in the space under the units drop down menu.

Map Measurement Tool:					
Measurement Units: Not certified for targeting.					
meters \$					
kilometers					
meters					
feet					
miles					
yards					
nautical miles					

8.0 (U) Map Layers

(U) OMAR offers a library of digital raster map backgrounds.

(U) Layer Switcher

(U) The Layer Switcher provides the capability to turn on/off various map overlays and reference data.

- Base Layer
 - Reference Data OMAR defaults to the Blue Marble reference data
- Overlays Provides the option to turn on/off the following overlays using the appropriate check box
 - OMAR Imagery Coverage footprints depicting imagery coverage
 - \circ $\;$ Bound Box bound box designated by the user $\;$
 - DD Grid Decimal Degree grid (scales based on zoom level)
 - DMS Grid Degree, Minutes, Seconds Grid (scales based on zoom level)

Layer Switcher:
Base Layer
 Reference Data
Overlays
DD Graticule
DMS Graticule
Sound Box
🗹 ngaiost



9.0 (U) Footprint Legend

(U) Colored footprints have been added to the Map Layer where a user will be able to locate format or sensor on the map by its color.

Footprint Legend:
cadrg
ccf
adrg
dted
jpeg
jpeg2000
landsat7
nitf
tiff
mpeg

10.0 (U) Imagery Search Results

(U) Once you have entered the desired search criteria, select the **Search** button to view the results of the search. There are two search buttons one at top left of the display and one on the bottom left of the display.

Imagery Search Results										
OMAR™ EXPORT SEARCH					Query Ma	p ngaiost				
Inits DD ÷			ID	THUMBNAIL	All Image VIEW	Metadata File Links	MISSION	COUNTRY	TARGET ID	Map Measurement Tool: Measurement Units:
✓ Use Spatial										Not certified for targeting.
Use Bound Box Bound Box Search:	6	2	<u>481</u>		Raw Ortho	2013-03-26T17:59:49.406Z				Layer Switcher: Base Layer
Lower-Left Lat/Lon: -159.2578125,-236.6015625				Las GOM	5					Reference Data Overlays DD Graticule
Upper-Right Lat/Lon: 159.2578125,236.6015625	6		<u>480</u>		Raw Ortho	2013-03-26T17:59:49.406Z				DMS Graticule Sound Box Ingaiost Footprint Legend: cadre
Point Radius Search: Center Lat/Lon: 0,0 Radius in Meters: 0	6	2	<u>479</u>		Raw Ortho	2013-03-26T17:59:49.407Z				ccf adrg dted jpeg jpeg2000 landsat7 nitf tiff
Temporal Search:	Sh	owing	1 to 1	0 of 31 entries		10 ¢ First P	Previous Pag	e 1 of 4 Ne	xt Last	mpeg
♂ 31										

10.1 (U) Image

(U) After a search has been completed the display will show Thumbnails and Medata. At the bottom of the display a box that looks like a disk will list the number of images that was found on the search. For a federated search there could be more than one disk displayed. There is a check box that will select the disk to view the images. If the box is not checked then the image cannot be viewed.



(U) For the Image section of the display there will be an ID listed for the image, a thumbnail and a section labeled VIEW. Under VIEW there are two buttons labeled Raw and Ortho where, Raw will display the image with no rectification and Ortho will be rectified.



Unclassified

11.0 (U) View of Metadata

(U) There are five buttons at the top center of the display. When one is selected the user will be able to see the image information of the image.



11.1(U) Information for the button Image

- *Id* integer given to each image as they are ingested into OMAR
- *Thumbnail* preview of the image
- View option to view raw or Orthorectified
- *Width* width of image in pixels
- *Height* height of image in pixels
- *Bands* number of bands within the electromagnetic spectrum that the image contains
- *R-Levels* number of resolution levels
- GSD X
- GSD Y
- *Bit Depth* how many bits represent each pixel
- Entry
- *Min Lat Lon* minimum east-west geographic coordinate in the image
- Max Lat Lon maximum north-south geographic coordinate in the image
- Center Lat Lon

		Query	Мар	ngaiost			
			mage 🔾 Me	tadata 🔾 Fil	e 🔾 Links		
ID	THUMBNAIL	VIEW	WIDTH	HEIGHT	BANDS	RLEVELS	GSD X
<u>485</u>		Raw Ortho	4872	3248	3	8	0.0626012696262807
<u>484</u>		Raw Ortho	15696	49564	1	11	0.799584311027141
<u>483</u>		Raw Ortho	4077	4092	3	7	0.216196532548034

11.2 (U) Information for the button Metadata

- *Id* integer given to each image as they are ingested into OMAR
- Thumbnail preview of the image
- Raw / Ortho
- *View* option to view raw or Orthorectified (opens the image in the viewer)
- *Acquisition Date* the time and date the image was taken
- *Mission* mission number representing which asset captured the image
- *Country* unique two-letter identifier given to each country
- Target ID
- *BE*
- *Sensor* ID- sensor type that acquired the image (e.g., VIS, MS, etc.)
- *IID* unique identifier given to each image
- File Type
- Class Name
- *NIIRS* National Imagery Interpretability Rating Scale a scale used to measure the overall quality of the image
- *Image Id* unique identifier given to each image

		Query	Мар	ngaiost				
			nage 💽 Me	tadata 🔾 File	Links			
ID	THUMBNAIL	VIEW	ACQUISI	TION DATE	MISSION	COUNTRY	TARGET ID	E
<u>485</u>		Raw Ortho	2011-12-17	F22:26:130Z				
<u>484</u>		Raw Ortho	2011-07-081	F06:31:390Z	IKONOS	AF		
<u>483</u>		Raw Ortho	2013-03-261	Г18:47:52.857Z				

11.3 (U) File

(U) Information for the button File

- *Id* integer given to each image as they are ingested
- *Thumbnail* preview of the image
- Raw / Ortho
- *View* option to view raw or Orthorectified (opens the image in the viewer)
- Filename physical location in the OMAR file system

		Query	Мар	ngaiost	
			nage 🔾 Me	tadata 💿 File	CLinks
ID	THUMBNAIL	VIEW			FILE
<u>485</u>		Raw Ortho	/data/test_ /2011Dec17	suite/raster/o _222613_1906	disk1/pearl 598_54fb51e3bd1311ccb0d27d8528902500.ntf
<u>484</u>		Raw Ortho	/data/test_ /AF/08JUL1	suite/raster/o 11K0101000po	disk1 9_648246_pan_0000001.ntf
<u>483</u>		Raw Ortho	/data/test_	suite/raster/o	disk1/US/bakersfield/16574078.tif

11.4 (U) Links

Information for the button Links

- *Id* integer given to each image as they are ingested
- *Thumbnail* preview of the image
- Raw / Ortho
- *View* option to view raw or Orthrectified (opens the image in the viewer)
- WMS GetCapabilities XML code for WMS call to view imagery elsewhere
- *WMS GetMap* returns a screen sized JPEG chip for the image
- *Get KML* generates a KML file for the image
- Super Overlay generates a super overlay KML file for the image

11.5 (U) Web Feature Service (WFS)

(U) OMAR provides the capability to create an XML document that identifies imagery, which matches a certain set of features within the image metadata. With each image in OMAR comes a host of features that are searchable via URL. See Appendix for more details and examples.

11.6 (U) Web Coverage Service (WCS)

(U) OMAR provides the capability to return a chip of an image that fits inside a specified BBOX. The service can be configured to return a chip of either a specific image or all images in OMAR that exist inside a specified BBOX. See Appendix for more details and examples.

12.0 (U) Viewing Imagery

(U) To view an image, click on a *Thumbnail* in the *Results Window* or on either *Raw* or *Ortho* link in the *View* column.

(U) OMAR image viewing is possible in either of two modes, *Orthorectified* and *Image Space*. In *Orthorectified* space, the image is Orthorectified to the underlying elevation surface using the applicable projection. In this mode it represents a map view. Note that, in many cases, the apparent image shape/boundaries will be deformed depending on the image acquisition geometry and terrain relief characteristics.



OMAR Orthrectified View

(U) In *Image* space, the image is displayed as it was originally acquired (no rectification).

Unclassified



OMAR Image View

12.1 (U) Common Elements

(U) The Orthorectified and Image viewers share many common user interface components.

12.2 (U) Toolbar Buttons

(U) At the top of the page, there are five buttons available to the user, as described below.

⋒	OMAR™ Home	New Search	Export -	View -	Share	

12.3 (U) OMAR™ Home

(U) This button returns the user to the OMAR home page.

OMAR™ Home

12.4 (U) New Search

(U) Will allow the user to start a new search

New Search

12.5 (U) Export

12.5.1 (U) In *Orthorectified* view, the following export choices are available:

- *JPEG* creates a JPEG file of the image displayed in the viewport
- *PNG* creates a PNG file of the image displayed in the viewport
- *PNG 8-bit* creates an 8 bit PNG file of the image displayed in the viewport
- *Geotiff* creates a GEOTIFF file of the image displayed in the viewport
- *Geotiff 8-bit* creates an 8 bit GEOTIFF file of the image displayed in the viewport
- *Geo Jpeg 2000* creates a GEO JPEG 2000 file of the image displayed in the viewport
- *Geo Jpeg 2000 8-bit* creates an 8 bit GEO JPEG 2000 file of the image displayed in the viewport
- *Template* provides the capability to save the view as an annotated product
- *OGC WMS Capabilities* provides a web page containing XML coded metadata about the image
- *KML* creates a KML file of the imagery for use in external GEOINT tools such as Google Earth
- *KML Superoverlay* This is similar to a normal KML Query however a Superoverlay file is optimized for Google Earth and its caching scheme. It creates a directory of links to image tiles at different zoom resolutions and caches them such that when a user returns to the same spot at a previous zoom level, the image does not need to be reloaded.
- *KMZ PNG* creates a KML with the currently displayed viewport image attached as a PNG (no transparency)
- *KMZ PNG Transparent* creates a KML with the currently displayed viewport image attached as a PNG (with transparency)
- *KMZ JPEG* creates a KML with the currently displayed viewport image attached as a JPEG (no transparency)



12.5.2 (U) In *Image Space North Up* view, the following export choices are available:

- *JPEG* creates a JPEG file of the image displayed in the viewport
- *PNG* creates a PNG file of the image displayed in the viewport
- *GIF* creates a GIF file of the image displayed in the viewport
- *Template* provides the capability to save the view as an annotated product
- *OGC WMS Capabilities* provides a web page containing XML coded metadata about the image

Export -	View -	Share	
JPEG			
PNG			
GIF			
Template			
OGC WMS Capabilities			

12.5.3 (U) In *Image Space Up is Up* view, the following export choices are available:

- *JPEG* creates a JPEG file of the image displayed in the viewport
- *PNG* creates a PNG file of the image displayed in the viewport

- *GIF* creates a GIF file of the image displayed in the viewport
- *Template* provides the capability to save the view as an annotated product
- *OGC WMS Capabilities* provides a web page containing XML coded metadata about the image

Export -	View -	Share		
JPEG				
PNG				
GIF				
Template				
OGC W	OGC WMS Capabilities			

12.5.4 (U) The Template

The Template capability allows the user to save the current viewport, formatted within a basic annotated framework. The header displays Classification, Image ID, Country Code, Map and North Arrow. Each of these headers can have different colors selected.


Template Export

(U) After the Template has all of the information enter then the user can download the Template as a PDF file. A message will be displayed showing the download progress.

OMAR™ Home	Export -	Previous Image	Next Image	
	Downloa		49246 pap 0	000004
	Country: u	us	140240_pan_0	000001
			C. C. C.	

(U) Fields are populated automatically where possible and can be manually specified as required.

12.5.5 (U) Orthorectified Multilayers the following export choices are available.

• *OGC WMS Capabilities* – provides a web page containing XML coded metadata about the image

- *KML* creates a KML file of the imagery for use in external GEOINT tools such as Google Earth
- JPEG creates a JPEG file of the image displayed in the viewport
- *Geotiff* creates a GEOTIFF file of the image displayed in the viewport
- *Geotiff 8-bit* creates an 8 bit GEOTIFF file of the image displayed in the viewport
- *Geo Jpeg 2000* creates a GEO JPEG 2000 file of the image displayed in the viewport
- *Geo Jpeg 2000 8-bit* creates an 8 bit GEO JPEG 2000 file of the image displayed in the viewport

Export -	View -	
OGC WI	MS Capabi	lities
Jpeg		
Geotiff		
Geotiff 8	-Bit	
Geo Jpe	g 2000	
Geo Jpe	g 2000 8-E	Bit

12.6 (U) View

View -

- Orthrectified the image and orients it with north being up
- Image Space (North) North up as originally acquired (no rectification)
- Image Space (North) North up as originally acquired (no rectification),
- *Multi Layer Viewer* Orthorectified the image and orients it with north being up with the ability to apply additional layers from NGA
- Detailed Metadata A listing of the images metadata
- *WMS Logs* Gives Start Date, Time, GSD, Width , Height, Layer, Formant and URL. Note this is the same for image space called Chip Log

ld user	Start Date	Internal Time (s)	Render Time (s)	Total Time (s)	Mean Gsd (m)	Width	Height	Layers	Styles	Format	Url
20,895 doconnor	2013-03-27 12:21:06.4	560.122	0.031	0.153	2.5	891	552	3077ddfe4e398e108a78118026c930637b76b94c1798a100f90e717f1b615cf3	3	image/jp/	egurl
20,894 doconnor	2013-03-27 12:16:09.5	590.428	0.042	0.47	1.371	891	552	3077ddfe4e398e108a78118026c930637b76b94c1798a100f90e717f1b615cf3	3	image/jpe	egurl
20,893 doconnor	2013-03-27 12:03:11.57	710.146	0.016	0.162	70.762	891	552	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/jp/	egurl
20,892 doconnor	2013-03-27 11:46:33.56	350.083	0.08	0.163	155.227	1,091	572	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/gif	if <u>url</u>
20,891 doconnor	2013-03-27 11:45:50.34	60.086	0.016	0.102	70.762	891	552	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/jp/	egurl
20,890 doconnor	2013-03-27 11:44:38.90	060.048	0.016	0.064	155.227	1,091	572	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/gif	if <u>url</u>
20,889 anonymousUse	r2013-03-27 11:27:46.48	330.398	0.058	0.456	32.21	892	553	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/pr	ng <u>url</u>
20,888 doconnor	2013-03-27 10:49:03.33	360.398	0.121	0.519	32.21	892	553	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/pn	ng <u>url</u>
20,887 doconnor	2013-03-27 10:48:32.79	910.422	0.02	0.442	32.258	891	552	4f3751bfecc9ef64f6cfa66ef08135d4be195ccbc051fb95f9a00bbfe080b420		image/jpr	egurl
20,886rsholmes	2013-03-27 10:46:00.9	460.274	0.006	0.28	19.109	256	256	be8c3ed3588285c77f9c46a4432072df6af52f49627f0fe1642e575a6905eb81		image/pr	ng url

• *Reset* – resets all image viewing parameters and zooms out all the way

View -	Share				
Image Space (North)					
Image	Space (Up	ls Up)			
Orthor	ectified Mult	i Layer			
Detaile	ed Metadata				
WMS I	_ogs				

12.7 (U) Share

Share

(U) This button provides a popup with a link to the current display, allowing easy sharing with other users. This shared link preserves all the formatting applied before selecting the **Share** button.

Сору	to clipboa	rd: Ctrl-	⊦C, Enter
http://1	0.0.10.32	:8080/o	mar/map
Γ	Cancel		OK

12.7.1 (U) Map Center:

(U) The Map Center displays the Lat / Long of the center of the image in the viewer.

Map Center:
DD:
33.485602061681, 65.7002705
DMS:
332908.17N 0654200.97E
MGRS:
41SQT5089408386
Apply Reset

12.8 (U) Open Source Software Image Map (OSSIM) Tools

(U) OMAR offers a host of OSSIM tools for image processing. To take advantage of these tools, simply click on an image thumbnail from the imagery search results page and adjust the controls in the *Image Adjustments* section in the left hand pane.

Image Adjustments:						
Interpolation:						
bilinear 🗘						
Brightness: 0						
Contrast: 1						
Reset						
Sharpen:						
none 🛊						
Dynamic Range Adjustment:						
Automatic \$						
Region:						
viewport \$						
Band:						
default 🛊						

12.8.1 (U) Interpolation

(U) Interpolation describes the method in which unknown pixels in an image are generated from known pixel values. Each interpolation method uses a different set of neighboring known pixels to determine the unknown pixel value. There are different levels of interpolation that OMAR offers, listed here in order increasing complexity (and quality, generally speaking)

- bilinear (default)
- nearest neighbor

- cubic
- sinc

12.8.2 (U) Brightness

(U) Adjusting the brightness (values range from -1 to +1) will raise or lower the overall brightness of the image.

12.8.3 (U) Contrast

(U) Adjusting the contrast (values range from 0 to 2) will cause brighter pixels to become brighter and darker pixels to become darker.

12.8.4 (U) Reset

(U) Resets the brightness and contrast back to default setting.

12.8.5 (U) Sharpen

- *none* no edge filtering done
- *light* runs a light filtering algorithm to bring out edges
- *heavy* runs a heavy filtering algorithm to bring out more edges

12.8.6 (U) Dynamic Range Adjustment

(U) The DRA feature runs a contrast enhancing algorithm that allows users to brighten up an image in areas that may appear dark under low or no stretch. To enhance contrast, the algorithm will select out different portions of the Gaussian distribution and remap the pixels (i.e. spread them out) along the axis of possible pixel brightness. For example, an 8-bit image will have brightness values from 0-255, or 256 possible brightness values from 0 (completely black) to 255 (completely white).

(U) In general, an image with very low contrast (a "flat" image) consists of a narrow grouping of pixels around a mean brightness value (a "narrow grouping") and for viewing enhancement will benefit from spreading the pixels further out along the x-axis ("brightness bins").

• Automatic – default; calculates pixel spread by statistical mean

- *1st Std* pixels from +/- 1 standard deviation are remapped
- 2nd Std pixels from +/- 2 standard deviations are remapped
- *3rd Std* pixels from +/- 3 standard deviations are remapped
- *No Adjustment* no contrast stretch.

(U) See Figures 10-14 for examples of the DRA effect.



12.8.7 (U) Region

(U) This selection specifies how to apply the sharpening and/or contrast filters.

Unclassified

- *global* apply to the entire image
- *viewport* apply to only the image region displayed on screen. The histogram is calculated for a 256x256 chip centered at the viewport center.

12.8.8 (U) Band

(U) A computer monitor displays colors as a combination of red, green and blue at different intensities. The band selections in OMAR allow users to change which image bands are represented by which color on the screen.

(U) For example, a multispectral image, as well as a multispectral image from GEOEYE, IKONOS and WORLDVIEW-1 commercial satellites will have the following four bands:

- Band 0: Blue (B)
- Band 1: Green (G)
- Band 2: Red (R)
- Band 3: Near IR (N)

(U) Note: The 8-band WORLDVIEW-2 imagery and other multi/hyper spectral imagery do not follow this pattern.

(U) The colors on the monitor cannot switch their order and will always follow a red, green and then blue pattern. Therefore, the default display in OMAR for multispectral images (0,1,2) will look strange because it displays the colors in the following manner.

- Red: 0 (Blue) All the blue in the image will appear red
- Green: 1 (Green) All the green in the image will appear green
- Blue: 2 (Red) All the red in the image will appear blue

(U) In order to display the colors in the correct order, select 2,1,0. Choosing to display only one band at a time will produce a gray scale representing the color intensity within that band.

default
0,1,2
2,1,0
1,0,2
1,2,0
2,0,1
0,2,1
0
1
2

(U) Note: At present OMAR does not support band 3, near IR.

12.8.9 (U) Orthorectified View

(U) The Orthorectified viewer presents an orthorectified representation of the image. This allows continuous cursor position readout to be provided below the image. Position is provided in geographic decimal degrees (DD) and degrees-minutes-seconds (DMS), as well as in the Military Grid Reference System (MGRS). The current display scale is also provided.

2 km 1 mi		Scale	e = 1 : 91K			
DD: 28.545390, -80.769134	DMS: 283243.41N 0804608.88W	MGRS: 17RNM2258457642				
	Unclassified					
Orthorectified Continuous Position Information Display						

12.8.10 (U) Orthorectification

(U) The user can allow OMAR to be more (or less) rigorous in calculating the geographic locations of pixels because OMAR "paints" the image on the screen as it calculates the pixels' locations, the more rigorous the process, the slower the image will be painted on the screen.

- *Rigorous* slower; uses the most rigorous sensor modeling available to map the pixels
- *Simple* (bilinear) faster; only uses the four corner point of the image to map the pixels

12.8.11 (U) Rotation

(U) Image rotation is accomplished by moving the slider until the image is in the desired position or by inputting the amount of rotation in degrees in the *rotate* box.

Rota	ite:					
0	Apply					
	1 1 1 1	+	+	+	-	
Reset North Up						

12.8.12 (U) Geopositioning

(U) In Image view, continuous readout of ground position is not available. However, discrete point geopositioning is accessible by selecting the **Point Drop** button S. When this button is activated, a left mouse click causes the display.

lmg: (2706, 6239)	Gnd: (28.6039184352418, -80.68247826901009) DD	HAE: -28	.8 m MSL: 1.1 m	SrtmTileSource	NitfRpcModel
	Unclass	fied			
	otions				

Geopositioning (Point Drop) Information Display

(U) The contents of the display, from left to right, include the following:

- 1 Img image coordinates (sample, line)
- 2 Gnd ground coordinates, in optional units:
 - a latitude, longitude; decimal degrees (DD)
 - b latitude, longitude; degrees, minutes, seconds (DMS)
 - c Military Grid Reference System (MGRS)
- 3 HAE height above ellipsoid
- 4 MSL height above mean sea level
- 5 elevation surface type
- 6 projection type (e.g. sensor model)

(U) The units of the point position display are selectable in the left panel.



Point Position Display Unit Selection

(U) Note that the difference between HAE and MSL represents the geoid-ellipsoid separation at that point on the earth's surface.

12.8.13 (U) Position Quality Evaluator

(U) The Position Quality Evaluator (PQE) is integrated with the geopositioning capability described in the previous paragraph. <u>It is only available for RPC images</u> having valid bias and random error components in their metadata. This function propagates the previously mentioned line-of-sight (LOS) error components and the elevation model uncertainty through the imaging ray/surface intersection geometry to estimate geopositioning accuracy. The estimated accuracy is displayed graphically via an error ellipse and numerically through the PQE panel on the left side of the page. If the image metadata does not support PQE computations, the ellipse will not be displayed and the panel content will be absent.

(U) It is important to emphasize that this is an ESTIMATE of probable position error and NOT a guarantee of maximum position error.



Panel and Associated Error Ellipse

(U) The contents of the panel include the following:

- *CE/LE* circular/linear error (horizontal/vertical)
- *SMA/SMI* semi-major/semi-minor axes (radii)
- *SMA AZ* semi-major axis azimuth
- Probability Level

(U) Note that the probability level is currently selectable at the following:

- *0.5P* 50% circular error probably (CEP)
- 0.9P 90% map accuracy standard (MAS)
- 0.95P 95% 2-sigma

12.9 (U) Map Measurement Tool

(U) Selection of the path measurement provides the capability to draw a line (or path) directly on the image. A double-click terminates the draw function and fills the panel. The panel contains the following information:

- *Geodetic Dist* curvilinear geodetic distance (by Vincenty's method)
- *Rect Dist* rectilinear (straight line) distance
- *Azimuth* azimuth (cw from north) from point 1 to point 2

(U) Can measure in : Kilometers, meters, feet, miles, yards and nautical miles

Map Measur	ement Tool:
NOT CERTI	FIED FOR TARGETING
Measuremen	t Units:
kilometers	-

(U) The *Map Measurement Tool* is use in conjunction with the *path length* and *polygon area* tools on the Navigation bar to measure distance or area.

12.9.1 (U) Measuring Path Length

- 1 Select the desired unit from the *Map Measurement Tool* drop-down menu
- 2 Select the *path length* tool from the Navigation bar

- 3 Move the cursor onto the map and click a point for the path start
- 4 Move the cursor to the desired end point and double click to complete the path.
- 5 Note the distance in the area under the units drop-down menu

12.9.2 (U) Measuring Polygon Area

- 1 Select the desired unit from the *Map Measurement Tool* drop-down menu
- 2 Select the *polygon area* **b**tool from the Navigation bar
- 3 Move the cursor onto the map and click a point to start the polygon
- 4 Move the cursor to the next location on the map and click to establish the next vertex of the polygon. Note: A polygon requires a minimum of 3 vertices.
- 5 Close the polygon by double-clicking on the start point
- 6 Note the area in the space under the units drop down menu

Map Measurement Too	l:
Measurement Units: Not certified for target	ing.
meters \$	
kilometers	
meters	
feet	
miles	
yards	
nautical miles	

12.9.3 (U) Predefined AOI Chipping Formats

(U) This capability is only in the image space allows the use of dimension presets for quick extraction and insertion of image chips into other presentation frameworks such as PowerPoint. The user interface for this capability is shown with two examples in the drop-down menu.

Unclassif	ied	
AOI: Custom	Output Scale:	Image 💌
Large 4X3: 800x600 PowerPoint 1: 976x780		357

(U) If **Custom** is selected, the popup menu allows the user to enter any dimensions for immediate use. The numeric dimensions must be separated by an "x".

(U) The "Output Scale" may be specified by choosing one of the following:

- Screen AOI is dimensioned in screen space
- *Image* AOI is dimensioned in actual image space, that is, scaled to current image scale display and output at full resolution

(U) The output chip has the specified dimensions in both cases.

196x190	

(U) The content of the AOI drop-down menu can be edited by an admin by selecting **ChipFormat** under the *Edit Tables* section of the *Home Page*. At that time a new format is created by clicking on **Enter New Chip Format** and entering a user defined label and the desired width/height of the AOI.

ip i onnat Lis	t			
ld	Label	Width	Height	Comment
1	Large 4X3	800	600	Temporary
	PowerPoint 1	976	780	NGA analyst recommended
			Ohio Format List	
_		OWAR - Home	Chip Format List	
		Create Chip Format		
			Label *	
			Label *	
			Label * Width *	
			Label * Width * Height *	
			Label * Width * Height *	

Figure 21. Chip Format Maintenance

12.10 (U) Base Layer / Overlay

(U) On the top right of the viewer that is a blue plus only on the Orthrectified selection a user will be able to deselect a federated disk or a bounding box



13.0 (U) Searching Video

13.1 (U) Federated Searching video

(U) There are different ways that a user can do a federated search using OMAR.

(U) Federated search came about to meet the need of searching multiple content sources with one query. This allows a user to search multiple databases at once in real time, arrange the results from the various databases into a useful form and then present the results to the user.

13.1.1 (U) Geographic Criteria

(U) OMAR provides four options to search geographically by specifying bounding box, point radius, date/time, query or map.

(U) Note: Input the geographical coordinates in the following formats by selecting the appropriate *Display Unit* drop-down menu at the top of the page:

- Decimal Degrees (DD),
- Degrees, Minutes, Seconds (DMS),
- Military Grid Reference System (MGRS)

13.1.2 (U) Bound Box

(U) This option is used to search video based on a bounding box of a specified size.

- *Lower Left* southwestern coordinate of bounding box
- *Upper Right* northeastern coordinate of bounding box
- *Clear Bound Box* action button to clear the contents of the bound box

OMAR™ EXPORT SEARCH
Jnits DD ‡
Search For: 💿 Raster 🔵 Video
✓ Use Spatial
 Use Bound Box
Bound Box Search:
Lower-Left Lat/Lon:
-159.2578125,-236.6015625
Upper-Right Lat/Lon:
159.2578125,236.6015625
OUse Point Radius
Point Radius Search:
Center Lat/Lon:
0,0
Radius in Meters:
0

13.1.3 (U) Search for Video on Point Radius

(U) This option is used to search Video based on a circle with a specified center and radius.

- *Map Center* enter coordinates to specify the center of the search
- *Radius in Meters* radius to specify the extent of the search
- Set Map Center action button to center the map based on the coordinates specified

Jnits DD 💠
Search For: 💿 Raster 🔵 Video
🗹 Use Spatial
Use Bound Box
Bound Box Search:
Lower-Left Lat/Lon:
-125.7718125,-170.9005625
Upper-Right Lat/Lon:
192.7438125,302.3025625
● Use Point Radius
Point Radius Search:
Center Lat/Lon:
33.486,65.701
Radius in Meters:
1

13.1.4 (U) Date/Time Criteria

(U) This option is used to search Video within a specific timeframe.

- *Start Date/Time* oldest date/time for which OMAR will search for video
- Stop Date/Time most recent date/time for which OMAR will search for video

Temporal Search:
Start ISO Date/Time:
2011-09-26T00:00:00.000+0000
····
End ISO Date/Time:
2011-09-27T00:00:00.000+0000

13.2 (U) Search Using Query

	Query	Мар	ngaiost
Named Queries 🗧 🗧			
And + +0	\$		
Reset Apply and Validate Show	·)		

(U) Below lists all of the different Medata Records that can be query on. They can be use one at a time or stringed together for a better more accurate query.

13.2.1 (U) Metadata Criteria

Raw CQL Record ID

Filename Width Height Ground Geom Start Date End Date Index Id			
	Query	Мар	ngaiost
Named Queries Raw CQL And Reset Apr Filename Width Height Ground Geom Start Date End Date			

13.3 (U) Searching Using the Map

Index Id

(U) Select the map button form the top of the viewer. The bright colored polygons (aka footprints) on the globe represent areas that have been videoed and are in the OMAR database. The footprint colors are keyed based on the legend in the right panel.

(U) When no search criterion is entered, as in this case, all OMAR imagery that is contained within the bounding box on the screen is returned in date/time order starting with the most recent image.

(U) Note: Panning around the map or zooming to a different location after setting the map center, will cause the *Map Center* input box to update with the new center.



13.4 (U) Navigation Bar

(U) The *Navigation Bar* found at the top of the *Search* page provides a variety of functions that allows the user to navigate through the world map. Hover over any of the ten buttons in the *Navigation Bar* to view their function.



- Click and drag to pan map
- Click and drag to zoom into an area
- 🔎 Click to zoom in
- 🔎 Click to zoom out
- Click to zoom to full resolution
- 🔀 Click to zoom to the max extent
- Click and drag to specify an area of interest
- 🔽 Click to clear area of interest



13.5 (U) Export



13.5.1 (U) Keyhole Markup Language (KML Query)

(U) Keyhole Markup Language (KML) is an XML notation for expressing geographic annotation and visualization within <u>Internet</u>-based, two-dimensional maps and three-dimensional <u>Earth</u> browsers. KML was developed for use with <u>Google Earth</u>, which was originally named Keyhole Earth Viewer. It was created by <u>Keyhole</u>, Inc, which was acquired by <u>Google</u> in 2004. KML became an international standard of the <u>Open Geospatial Consortium</u> in 2008.^{[1][2]} Google Earth was the first program able to view and graphically edit KML files. Other projects such as <u>Marble</u> have also started to develop KML support.[[]

(U) When an AOI is selected from the map that query will be open and displayed in Google Earth.

13.5.2 (U) Keyhole Markup Language (KML Query Float Bbox)

(U) Is the same KML query but has a JavaScript library for displaying windowed content over top of web pages

(U) When an AOI is selected from the map that query will be open and displayed in Google Earth

13.5.3 (U) GeoJSON

(U) GeoJSON allows geographic data to be stored in a human-readable way that is generally more compact than <u>XML</u>.

(U) When an AOI is selected from the map that query will be open and display XML.

13.5.4 (U) GML - Geography Markup Language

(U) The **Geography Markup Language** (**GML**) is the <u>XML</u> grammar defined by the <u>Open Geospatial Consortium</u> (OGC) to express geographical features. GML serves as a modeling language for geographic systems as well as an open interchange format for geographic transactions on the Internet. Note that the concept of feature in GML is a very general one and includes not only conventional "vector" or discrete objects, but also coverage's and sensor data. The ability to integrate all forms of geographic information is key to the utility of GML.

(U) When GML is selected it can be open in a browser like Firefox and will display an XML text.

13.5.5 (U) Comma-separated values (CSV)

(U) A **comma-separated values** (**CSV**) file stores <u>tabular</u> data (numbers and text) in plain-text form. <u>Plain text</u> means that the file is a sequence of <u>characters</u>, with no data that has to be interpreted instead, as binary numbers. A CSV file consists of any number of <u>records</u>, separated by line breaks of some kind; each record consists of <u>fields</u>, separated by some other character or string, most commonly a literal comma or <u>tab</u>.

(U) CSV can be open in a number of different applications.

13.5.6 (U) Timelapse

(U) Timelapse is not used for Video only imagery files.

13.6 (U) Map Measurement Tool

(U) The *Map Measurement Tool* is use in conjunction with the *path length* and *polygon area* tools on the Navigation bar to measure distance or area.

13.6.1 (U) Measuring Path Length

(U) Select the desired unit from the *Map Measurement Tool* drop-down menu.

(U) Select the *path length* tool from the Navigation bar.

(U) Move the cursor onto the map and click a point for the path start.

(U) Move the cursor to the desired end point and double click to complete the path.

(U) Note the distance in the area under the unit's drop-down menu.

13.6.2 (U) Measuring Polygon Area

(U) Select the desired unit from the Map Measurement Tool drop-down menu

- (U) Select the *polygon area* **b**tool from the Navigation bar
- (U) Move the cursor onto the map and click a point to start the polygon

(U) Move the cursor to the next location on the map and click to establish the next vertex of the polygon. Note: A polygon requires a minimum of 3 vertices.

(U) Close the polygon by double-clicking on the start point

(U) Note the area in the space under the units drop down menu

Map Measurement Too	l:	
Measurement Units:		
Not certified for target	ing.	
meters +		
Theters +		
kilometers		
meters		
feet		
miles		
yards		
nautical miles		

13.7 (U) Map Layers

(U) OMAR offers a library of digital raster map backgrounds.

13.7.1(U) Layer Switcher

(U) The Layer Switcher provides the capability to turn on/off various map overlays and reference data

- Base Layer
 - Reference Data OMAR defaults to the Blue Marble reference data
- Overlays Provides the option to turn on/off the following overlays using the appropriate check box
 - OMAR video Coverage footprints depicting video coverage
 - Bound Box bound box designated by the user
 - DD Grid Decimal Degree grid (scales based on zoom level)
 - DMS Grid Degree, Minutes, Seconds Grid (scales based on zoom level)





13.8 (U) Footprint Legend

(U) Colored footprints have been added to the Map Layer where a user will be able to locate format or sensor on the map by its color. **Note mpeg is a lite blue**

Fo	otprint Legend:
	cadrg
	ccf
Π	adrg
	dted
	jpeg
	jpeg2000
	landsat7
	nitf
	tiff
	mpeg

13.9 (U) Imagery Search Results

(U) Once you have entered the desired search criteria, select the **Search** button to view the results of the search (Figure 6) there are two search buttons one at top left of the display and one on the bottom left of the display

OMAR™ EXPORT SEARCH				Query	Мар	ngaiost				
Units DD +						ile 🔾 Links				Map Measurement Tool:
Search For: Raster 💽 Video		ID	THUMBNAIL				FILENA	ME		Measurement Units:
✓ Use Spatial	0	2		/data/test_suite	/video/vid	eo/CV425	55E321_08APR05IJ00	01533IJCVCV000999.n	npg	Not certified for targeting.
• Use Bound Box										0 km^2
Bound Box Search:										
Lower-Left Lat/Lon:										Base Layer
-35.560017707602,136.88576027										Reference Data Overlays
Upper-Right Lat/Lon:	H									DD Graticule
-34.296589973227,139.62959572										Bound Box
Use Point Radius	11									Ingalost
Point Radius Search:										Footprint Legend:
Center Lat/Lon:										ccf
-34.928303840415,138.25767800										dted
Radius in Meters:										jpeg jpeg2000
0	Showing 1	1 to 1 of 1 entries					6	10 + First Previous	Page 1 of 1 Next Last	landsat7 nitf
Temporal Search:										tiff
A MA.A					_					
ଟ 🖠										
ngalost										
				Un	classif	ied				



13.9.1 (U) Video

(U) After a search has been completed the display will show Thumbnails and Medata. At the bottom of the display a box that looks like a disk will list the number of videos that was found on the search. For a federated search there could be more than one disk displayed. There is a check box that will select the disk to view the images. If the box is not checked then the videos cannot be viewed.



14.0 (U) Video Section

(U) For the video section of the display there will be an ID listed for the video, and a thumbnail.



14.1 (U) Metadata Buttons

(U) There are three buttons at the top center of the display. When one is selected the user will be able to see the video information.

OAll	💿 File	Links

14.1 1 (U) File

File

(U) Information for the button File

- *Id* integer given to each image as they are ingested
- Thumbnail preview of the image
- Filename physical location in the OMAR file system



14.1 2 (U) Links



(U) Information for the button Links

- *Id* integer given to each image as they are ingested
- Thumbnail preview of the image
- Get KML generates a KML file for the image

		⊖All ⊖File ●Links	
0	ID	THUMBNAIL	LINKS
	2		• <u>Get KML</u>

14.2 (U) Web Feature Service (WFS)

(U) OMAR provides the capability to create an XML document that identifies video, which matches a certain set of features within the image metadata. With each image in OMAR comes a host of features that are searchable via URL. See Appendix for more details and examples.

14.3 (U) Web Coverage Service (WCS)

(U) OMAR provides the capability to return a chip of a video that fits inside a specified BBOX. The service can be configured to return a chip of either a specific video or all videos in OMAR that exist inside a specified BBOX. See Appendix for more details and examples.

14.4 (U) Viewing Video

(U) To view a video, click on a *Thumbnail* in the *Results Window*. Note the video ID will be displayed at the top of viewer.



Figure 7. OMAR Video View

14.4.1 (U) Home/KML

(U) Once in OMAR Viewer, a user has the ability to execute any of the following actions:

- OMAR Home Goes back to the home page
- *Generate KML* create a KML of the clip (located at the top of screen)



Note: In order for the video to play, the flash player plug-in must be installed in the browser.

Unclassified

15.0 (U) OMAR Web Mapping Service (WMS) Interface

15.1 (U) Keyhole Markup Language (KML) Network Links

(U) OMAR provides incredibly rapid and agile access to the repository from external GEOINT tools via KML network links. The tools that are currently available include the following pre-built network links, available for download from the OMAR Welcome page under **KML Network Links**:

(U) Most Recent Images for View

This KML provides the most recent <user specified number> images available in OMAR, given certain geographic criteria (i.e. bounding box). This helps determine what OMAR data is available in the user's area of interest.

(U) Most Recent Videos for View

This KML provides the most recent <user specified number> of 1-minute video clips available in OMAR, given certain geographic criteria (i.e. bounding box). This helps determine what OMAR data available in the user's area of interest.

(U) Most Recent Days Images for View

This KML places green wire frames on the globe, representing imagery that OMAR has ingested within the last <user specified number> days. This helps determine whether OMAR has recent imagery available in the user's area of interest.

(U) Most Recent Videos for View

This KML places a red wire frames on the globe for every 1-minute video clip that OMAR has ingested within the last <user specified number> number of days. This helps determine whether OMAR has recent video available in the user's area of interest.

15.2 (U) Viewing OMAR Imagery in Google Earth

(U) To view video stored in OMAR for the area in your view port:

- 1 Login to OMAR
- 2 Under **KML Network Links**, next to **Most Recent Images for View** enter the number of videos for which you want to query OMAR
- 3 Click Most Recent videos for View and download the KML file
- 4 Open the KML file in Google Earth
- 5 Navigate and zoom to an area of interest in Google Earth

- 6 In the temporary places folder, right-click on the **OMAR Last <#> videos For View** KML file and click **Refresh**.
- 7 Click the **+** sign in the left-hand column to expand the **OMAR Last <#> Days videos** folder. Up to ten images in that area are displayed.

(U) Note: videos are date stamped. Ensure that the date/time slide ruler is expanded so that the appropriate date range is displayed.



Figure 25: Image Overlay in Google Earth

15.3 (U) Video Playback from OMAR in Google Earth

(U) The video network link will fetch the last 10 Videos (or however many days you selected) available for the current AOI in Google Earth. Select the appropriate thumbtacks to view the 1-minute playback.



Figure 26: Video Footage Coverage in Google Earth

16.0 (U) Quick Start Query Flat Frame Imagery and Video

16.1 (U) Query Flat Frame Imagery

16.1.1 (U) Login to OMAR

Please Login	
Login ID	
Password	
Remember me	
	Login

16.1.2 (U) Select Search to go to the query page



16.1.3 (U) Select Raster for imagery

Jnits DD	\$	
earch For:	 Raster 	O Video
🗹 Use Spa	tial	
Use Bour	nd Box	

16.1.4 (U) Enter your Lat/Long into the point Radius

Point Radius Search:	ſ
Center Lat/Lon:	
0,0	
Radius in Meters:	
0	

16.1.5 (U) Enter the Date/Time for your query.

Temporal Search:	
Start ISO Date/Time:	
]
End ISO Date/Time:	

16.1.6 (U) Click on Search button



16.1.7 (U) View queried images from the Federated disks.

(U) If you have a number of federated users then there can be a number of disks displayed at the bottom of the display. If all disks are selected then all returned images would be displayed. If not then each will need to be viewed.



16.2 (U) Query Video

16.2.1 (U) Login to OMAR

Please Login	
Login ID	
Password	
Remember me	
	Login

16.2.2 (U) Select Search to go to the query page



16.2.3 (U) Select Video for video



16.2.4 (U) Enter your Lat/Long into the point Radius

Point Radius Search:	
Center Lat/Lon:	
0,0	
Radius in Meters:	
0	

16.2.5 (U) Enter the Date/Time for your query.

Temporal Search:	
Start ISO Date/Time:	
End ISO Date/Time:	

16.2.6 (U) Click on Search button



16.2.7 (U) View queried video from the Federated disks.

(U) If you have a number of federated users then there can be a number of disks displayed at the bottom of the display. If all disks are selected then all returned video would be displayed. If not then each will need to be viewed.



17.0 (U) Appendix

17.1 (U) Setup a Federated User

17.1.1 (U) Federation from the OMAR home page

(U) To setup a Federated User it is an Admin function so only an Administrator can perform this function.

(U) Go to the bottom of the home page and move down to the Admin section.

-							
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17.1.2 (U) Select Federation Page

(U) Select the first field Federation from the Admin section on the OMAR[™] home page

(U) This will display the federation page so you can federate with another server.

(U) V-Card - Is the identifying information of your OMAR[™] server. The nickname of the V-Card is the most important to add and is used as the main display name by all other servers this OMAR[™] is federated to.

(U) Chat Server – IP, Domain, Port, Username and Password of the jabber server used as the federation server.

(U) Federated Chat Room – The Administrator that is setting up the federation will enter this information. The jabber server will have a room created that your OMAR[™] server can log into and will be used to pass the V-Card information to all connected OMAR[™] servers.

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17.1.3 (U) Example of a Federated Page

- (U) Here is an example of what a federated page will look like.
- (U) Note that only the nickname was entered for the V-Card Profile.
- (U) All of the fields were filled for the Chat Server Settings

(U) Federated Chat Room Setting was given a room ID, Password and was enabled so the server could be federated. If you want to remove your server from the chat room then deselect the enable button and hit the apply button.

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17.2 (U) Common Query Language (CQL)

17.2.1 (U) Imagery Examples

(U) Search for all image footprints that have width less than 10,000 pixels and have height less than 10,000 pixels.

CQL Statement: width < 10000 and height < 1000

Figure 27: CQL Example 1

(U) Search for all imagery that intersects the polygon with lon/lat values -180, -90; - 180, 90; 180, 90; 180, -90; -180, -90 and have a width greater than 1,000 pixels and a height less than 100,000 pixels and an acquisition date after 5/10/11 @ 15:08:18Z.

```
CQL Statement: INTERSECTS(ground_geom, POLYGON((-180 - 90, -180 90, 180 90, 180 -90, -180 -90))) and width > 1000 and height < 100000 and acquisition_date > '2011-05-10T15:08:18.000Z'
```

Figure 28: CQL Example 2

17.2.2 (U) Video Example

(U) Search for all video files that have "mpg" in the title.

CQL Statement: filename like `%.mpg'

Figure 29: CQL Example 3

		-
Column Name	Column Type	Supported Operators
width	long	=, <>, <, >, <=, >=
height	long	=, <>, <, >, <=, >=
number_of_bands	integer	=, <>, <, >, <=, >=
number_of_res_levels	integer	=, <>, <, >, <=, >=
gsd_unit	string	=, <>, like
gsd_x	double	=, <>, <, >, <=, >=
gsd_y	double	=, <>, <, >, <=, >=
bit_depth	integer	=, <>, <, >, <=, >=
data_type	string	=, <>, like
index_id	string	=, <>, like
filename	string	=, <>, like
image_id	string	=, <>, like
target_id	string	=, <>, like
product_id	string	=, <>, like
sensor_id	string	=, <>, like
mission_id	string	=, <>, like
image_category	string	=, <>, like
image_representation	string	=, <>, like
azimuth_angle	double	=, <>, <, >, <=, >=
grazing_angle	double	=, <>, <, >, <=, >=
security_classification	string	=, <>, like
security_code	string	=, <>, like
title	string	=, <>, like
isorce	string	=, <>, like
organization	string	=, <>, like

17.2.3 (U) Supported Search Parameters for Imagery

description	string	=, <>, like
country_code	string	=, <>, like
niirs	double	=, <>, <, >, <=, >=
wac_code	string	=, <>, like
sun_elevation	double	=, <>, <, >, <=, >=
sun_azimuth	double	=, <>, <, >, <=, >=
cloud_cover	double	=, <>, <, >, <=, >=
ground_geom	polygon	See Example
access_date	date time	=, <>, <, >, <=, >=
ingest_date	date time	=, <>, <, >, <=, >=
receive_date	date time	=, <>, <, >, <=, >=
file_type	string	=, <>, like
class_name	string	=, <>, like

17.2.4 (U) Supported Search Parameters for Video

Column Name	Column Type	Supported Operators
filename	string	=, <>, like
width	long	=, <>, <, >, <=, >=
height	long	=, <>, <, >, <=, >=
ground_geom	polygon	See Example 3
start_date	date	=, <>, <, >, <=, >=
end_date	date	=, <>, <, >, <=, >=
index_id	string	=, <>, like

17.2.5 (U) Supported Search Clauses

and or not

17.3 (U) Web Feature Service (WFS)

17.3 1 (U) Imagery Example

(U) Search for images that are of the file type NITF and have a NIIRS value of greater than.5. The URL would be constructed to look like:

http://omar./omar/ogc/wfs?request=getFeature&typename=raster_entry&filter=file_type='nitf' and niirs >.5

Figure 30: WFS Example 1

17.3.2 (U) Video Example

(U) Search for video started before 4/20/11 @ 10:00:22z and has a height more than 400 pixels. The URL would be constructed to look like:

http://omar./omar/ogc/wfs?request=getFeature&typename=video_data_set&filter=start_date < '2011-04-20 10:00:22' and height > 400

Figure 31: WFS Example 2

Feature	Туре	Feature	Example
access_date	dateTime	keep_forever	boolean
acquisition_date	dateTime	mission_id	string
azimuth_angle	double	niirs	double
be_number	string	number_of_bands	integer
bit_depth	integer	number_of_res_levels	integer
class_name	string	organization	string
cloud_cover	double	other_tags_xml	string
country_code	string	product_id	string
data_type	string	raster_data_set_id	long
description	string	receive_date	dateTime

17.3.3 (U) Supported Feature List for Imagery

entry_id	string	release_id	decimal
exclude_policy	string	security_classification	string
file_type	string	security_code	string
filename	string	sensor_id	string
grazing_angle	double	style_id	decimal
ground_geom	class com.vividsolu tions.jts.geom. Geometry		
gsd_unit	string	sun_azimuth	double
gsdx	double	sun_elevation	double
gsdy	double	target_id	string
height	long	tie_point_set	string
image_category	string	title	string
image_id	string	valid_model	integer
image_representation	string	version	long
index_id	string	wac_code	string
ingest_date	dateTime	width	long
isorce	string		

17.3.4(U) Supported Feature List for Video

Feature	Туре		
end_date	dateTime		
filename	string		
ground_geom	class com.vividsolutions.jts.geom.Geometry		
height	long		
index_id	string		
other_tags_xml	string		
repository_id	long		

start_date	dateTime
style_id	decimal
version	long
width	long